## **Amendments to the Specification**

Please replace the paragraph at page 22, line 16 through page 23, line 8 with the following amended paragraph:

Figs. 4A and 4B comprise a flowchart that summarizes an embodiment of the present invention employing the Viterbi inference algorithm for SLDSs, as described above. The steps are as follows:

Initialize LDS state estimates 
$$\hat{x}_{0|-1,i}$$
 and  $\Sigma_{0|-1,i}$ ; (Step 102)

Initialize  $J_{0,i}$ . (Step 102)

for  $i=1:T-1$  for  $t=1:T-1$  (Steps 104, 122)

for  $j=1:S$  (Steps 106, 120)

for  $j=1:S$  (Steps 108, 114)

Predict and filter LDS state estimates

 $\hat{x}_{i|\iota,\iota,j}$  and  $\Sigma_{i|\iota,\iota,j}$  (Step 110)

Find  $j \to i$  "transition probability"  $J_{\iota|\iota-1,\iota,j}$  end (Step 112)

Find best transition  $J_{\iota,i}$ , into state  $i$ ; (Step 116)

Update sequence probabilities  $J_{\iota,i}$  and LDS state estimates  $\hat{x}_{\iota|\iota,\iota}$  and  $\Sigma_{\iota|\iota,\iota}$  (Step 118) end

Find "best" final switching state  $i_{T-1}^*$  (Step 124)

Backtrack to find "best" switching state sequence  $i_{\iota}^*$  (Step 126)

Find DBN's sufficient statistics. (Step 128)

Please replace the paragraph at page 24, line 1 through line 5 with the following amended paragraph:

Namely, for a given set of observations  $Y_T$ , a distribution  $Q(X_T, S_T \mid \eta, Y_T)$  with an additional set of variational parameters h is defined such that Kullback-Leibler divergence between  $Q(X_T, S_T \mid \eta, Y_T)$  and  $P(X_T, S_T \mid Y_T)$  is minimized with respect to h:

$$\eta^* = \arg\min_{\eta} \sum_{S_T} \int_{X_T} Q(X_T, S_T | \eta, Y_T) \log \frac{P(X_T, S_T | Y_T)}{Q(X_T, S_T | \eta, Y_T)}.$$